

रोबोकम्पास-

ऑनलाइन ज्यामिति सॉफ्टवेयर
प्रस्तुति - आशुतोष आनन्द

- **ROBOCOMPASS** क्या है ?
- **ROBOCOMPASS** – प्रक्रिया
- **ROBOCOMPASS** –कार्य करने के **इंटरफ़ेस** को समझना ।
- **ROBOCOMPASS** –में विभिन्न ज्यामितीय निर्माण कमाण्ड जानना एवं प्रयोग करना सीखना ।
- ROBOCOMPASS** –सॉफ्टवेयर में बने ज्यामितीय निर्माण की फाइल को **सेव** करना और पहले से बनी फाइल को **ओपन** करना

ROBOCOMPASS (रोबोकम्पास)-विवरण

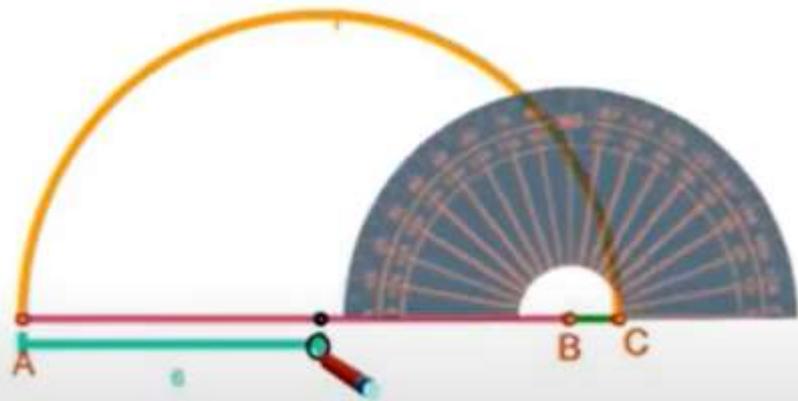
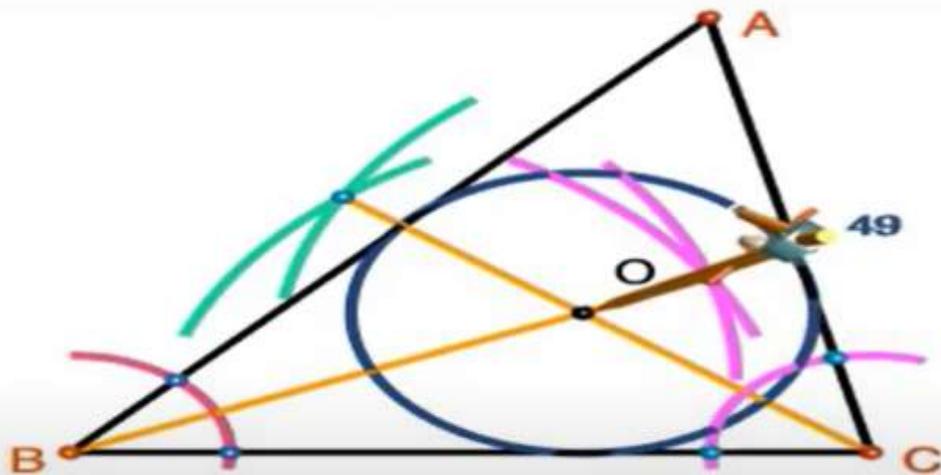
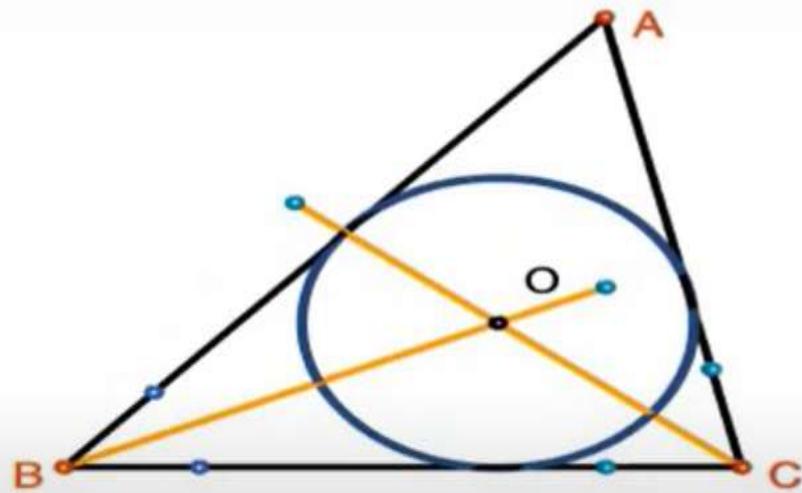
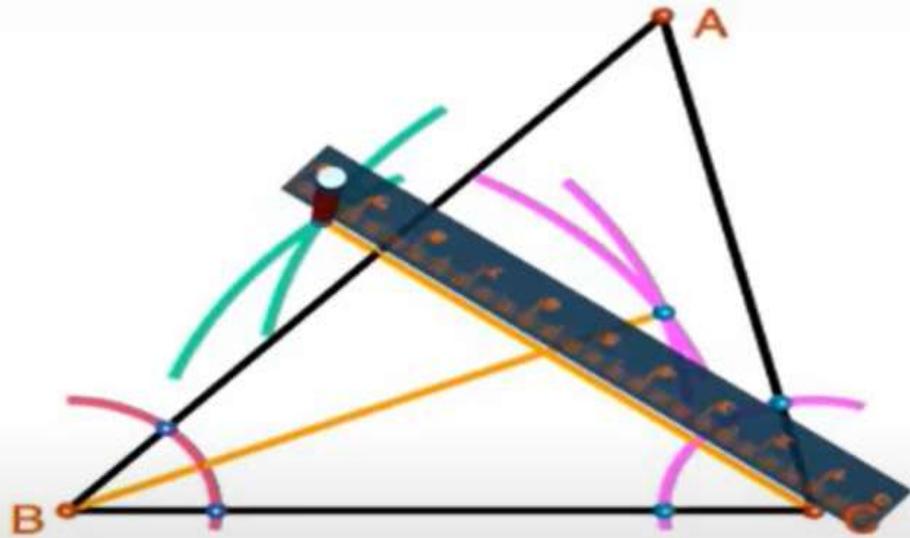
❖ यह एक ऑनलाइन **साँफ्टवेयर** है जिसके माध्यम से हम लगभग सभी ज्यामितीय रचनाएँ कर सकते हैं

• यह ज्यामिति बॉक्स में उपलब्ध विभिन्न Tools जैसे पटरी, परकार, सेट स्क्वायर, पेंसिल आदि को एनिमेटेड रूप देता है



- बिंदु
- रेखाखण्ड
- चाप
- वृत्त
- कटान बिंदु
- कोण बनाना

कोण की रचना
कोण की माप
रेखाखण्ड की माप
समान्तर रेखा खींचना
लम्ब खींचना



रोबो कम्पास (ROBOCOMPASS) - प्रक्रिया



ROBOCOMPASS पर कार्य करने के लिए सबसे पहले GOOGLE पर ROBOCOMPASS सर्च करें

About 5,820 results (0.38 seconds)

www.robocompass.com

Robocompass | A Robotic Geometry Box on 3D

Exactly as you do using a physical straightedge, compass and protractor. Open Robo Compass - Robocompass Tour Preview: What Users Say?

You've visited this page many times. Last visit: 23/9/20

Open Robo Compass

Practice Compass and StraightEdge constructions ...

Share Url

Command, Purpose and Examples. point(x, y), Example:- point(3, 4 ...

More results from robocompass.com »

chrome.google.com › webstore › detail › robocompass

RoboCompass

May 23, 2014 — This app lets you teach and learn Geometry exactly as you do using your Geometry Box.It has paper,a Straight Edge,a Compass,a Protractor,a ...

You've visited this page many times. Last visit: 7/7/20

robocompass

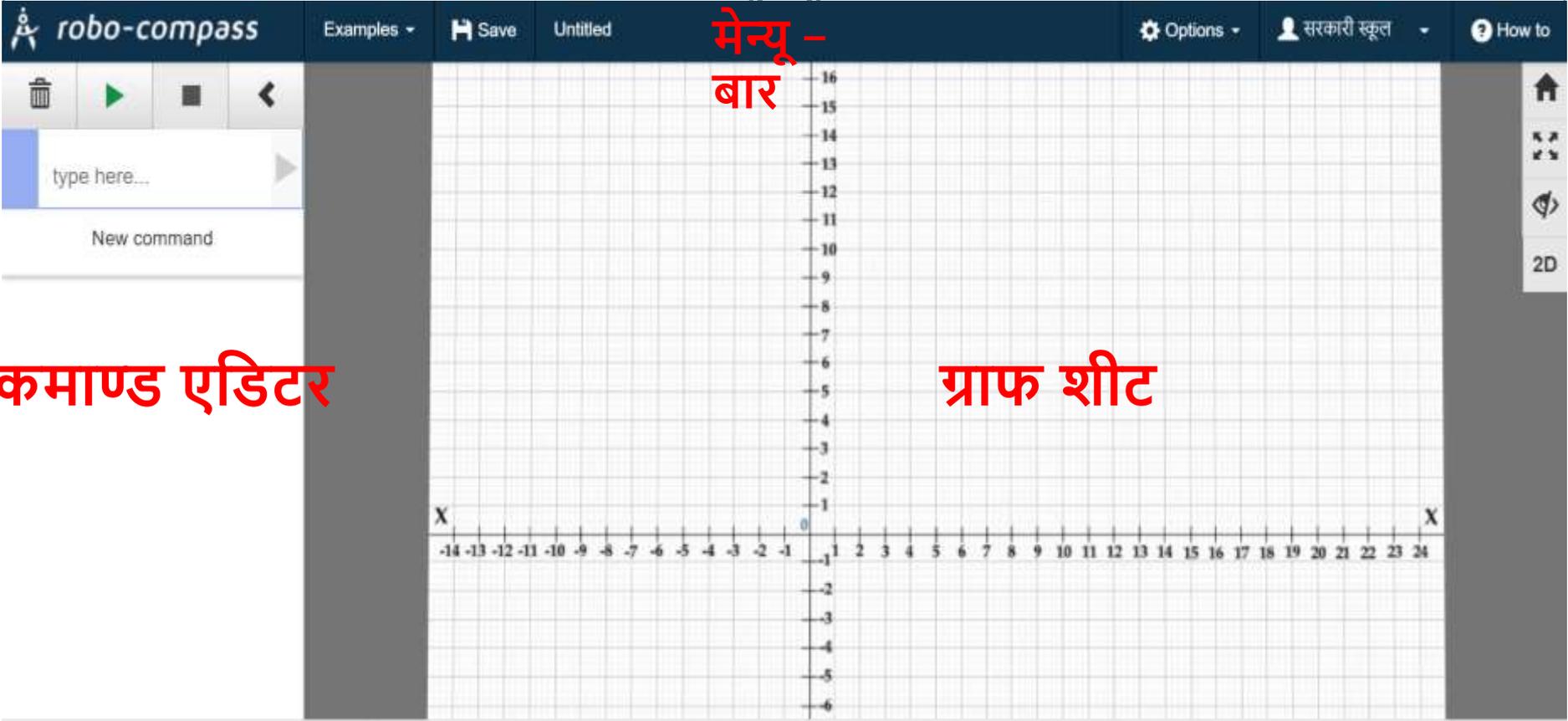
Teach and Learn

- Geometrical Constructions
- Transformations
- Patterns and Tessellations

Exactly as you do using a physical straightedge, compass and protractor.

OPEN ROBO COMPASS

- इंटरफ़ेस-



मेन्यू -
बार

कमाण्ड एडिटर

ग्राफ शीट

MENU BAR



Select the *Untitled* menu to save a worksheet.

Hint: Sign into RoboCompass using a *Gmail account* before saving a worksheet.

When the *Example* menu is selected, a dropdown list of example worksheets will display.

Hint: All example worksheets can be modified.

Take the Tour

To watch the RoboCompass demo click the *Take the Tour* button.

Sign in

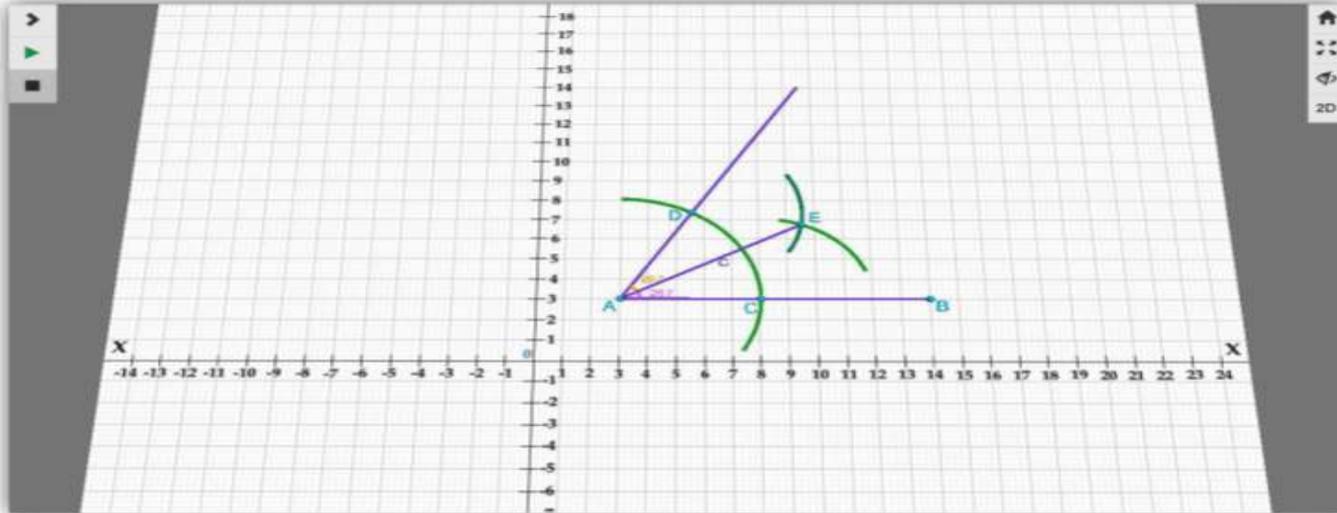
Select the *Sign In* button to sign into your Gmail account.

How to

Select *How to* for a list of supported commands.

GRAPHSHEET

Graphsheet: View the geometry output of entered commands in the command editor. The straightedge, setsquare, compass, protractor, and pencil graphics simulate the steps of the geometry construction for the corresponding commands.



Show Command Editor



Full Screen/ Exit



2D/3D View



Reset View



Hide Grid/ Show Grid

COMMAND EDITOR

A=point(2,10)

B=point(8,10)

line(A,B)

New command



Delete All

Play All

Stop

Hide Command Editor

Select "New Command" to add a new command item.

Individual delete

Individual Play

line(A,B)

- In the settings panel control options for:
- Play speed
 - Color
 - Label objects

Settings

Colors:

Show label: Label offset: X: 0 Y: 0

Comment:

type here...

Speed:

Apply this speed to all

-ड्राइंग कमाण्ड -



Drawing commands

Command	Purpose and Examples
<code>point(x, y)</code>	Example:- <code>point(3, 4)</code> or <code>A=point(3, 4)</code> where A is the label.
<code>line(x1, y1, x2, y2)</code>	Example:- <code>line(0,0,-2,5)</code> or <code>C=line(A, B)</code> where A, B are point labels. Length can be optionally given as <code>line(A, B, 3)</code> where 3 is length of segment.
<code>arc(originPoint, radius, angleFrom, upto)</code>	Example:- <code>arc(point(2, 2), 3, 40, 20)</code> Uses <code>point(2, 2)</code> as origin, 3 as radius and starts the arc from 40 degrees adding another 20 degree in an anticlockwise direction. A negative value for "upto" parameter will move clockwise. To copy a line, give the first parameter as line or two points as shown here <code>arc(point1, point2, originPoint, angleFrom, upto)</code>
<code>perp(line, passThroughPoint, length=10)</code>	Example:- <code>A=perp(line(1, 2, 3, 4), point(1, 2))</code> draws a perpendicular line to a given <code>line(1, 2, 3, 4)</code> passing through <code>point(1, 2)</code> . The last optional parameter of <code>perp</code> command is the length of the perpendicular line which defaults to 10.
<code>parallel(line, passThroughPoint, length=10)</code>	Example:- <code>parallel(line(1, 2, 3, 4), point(1, 2))</code>



angle(point1, point2, degrees)

Example:- `angle(A, B, 45, 1)` The two points A and B defines the base line. The ratio is an optional parameter which controls the position of the protractor. A value of 0 places it at A, 1 at B and 0.5 in the middle.

polygon(comma separated points)

Example:- `polygon(A, B, C)` draws a triangle where A, B, C are points

findangle(2 lines or a polygon)

Example:- `findangle(A, B)` finds the angle between two lines A, B or a polygon
`findangle(C)` (C is the label of polygon, in this case the method returns the first angle)

fill(A, B)

Fills the interior of shapes A,B. The shapes can be an arc, polygon or another fill. The command accepts any number of shapes. `fill(A)`, `fill(arc(0, 0, 3, 0, 360), D)`, `fill(polygon(2, 3, 4, 6, 1, 0))`



Command	Purpose and Examples
dist(point1, point2)	Calculates the distance between two points. Give a <code>dist(C)</code> if C is a line (i.e. segment)
X(point)	Gives the X coordinate of a point A. <code>A= X(point(2,1))</code>
Y(point)	Gives the Y coordinate of a point A. <code>B= Y(point(1,2))</code>
pos(polygon or line or arc, index)	Returns the point at a given index. If a polygon A has 4 points, <code>pos(A, 3)</code> returns the third point, Similarly if a line's label is B a index of 2 returns the end point. Example:- <code>pos(B, 2)</code>
intersect(object1, object2, index=1)	Intersects any two objects (except points).Example <code>G=point(intersect(D, E))</code> By default returns the first intersecting point, for second and third intersecting point, give 2 or 3 respectively. For example this <code>intersect(D, E, 2)</code> gives the second intersecting point.
reflect(object, line)	Reflects the object by a given line. Example:- <code>reflect(D, A)</code> where D is the label of point to reflect and A is the reflecting line

-ड्राइंग कमाण्ड-



rotate(object, angle, withrespectTo=point(0, 0))

Rotates the object by a given degree. By default, the rotation is with respect to origin (0, 0), which can be optionally overridden by giving the parameter withrespectPoint.

translate(object, x, y, withrespectTo=point(0, 0))

Translates the object by given x, y with respect to origin or by given withRespectTo parameter. `translate(arc(2, 3, 3, 0, 180), 2, 3, point(2, 1))` or `translate(G, 2, 4)`

dilate(object, scaleFactor, withRespectTo=point(0, 0))

Dilates the object by a given scaleFactor parameter. `dilate(point(3, 1), 2)`

project(point1, line)

Projects the input point on the line and returns the projected point. Example:- `project(A, line(0, 0, 1, 0))` projects the point A on the given line.

interpolate(point1, point2, ratio)

Example:- `interpolate(A, B, 0.5)` A ratio of 0.5 returns the midpoint of A, B

hide(comma separated labels)

Example:- `hide(A, B, C, D)` hides objects A, B, C, D. To show again use `show(A, B, C, D)`

group(comma separated objects)

Transformations can be applied on multiple objects simultaneously by creating a group. For example to rotate both a arc 'A' and a polygon 'B' together, use `C=group(A, B)` and then `D=rotate(C, 120)` where C is the label of the group. Groups can also be nested.

-अपना कार्य सुरक्षित करें-

SAVE ROBO WORKSHEETS

1. To save your work click the Untitled button. The Save dialogue box will open.

2. Type a title and description then click the Save Robo Button

Save

Title:
Target line in a Circle

Description:
Target line in a Circle

✓ saved successfully

Share Save Robo

Visit: <http://www.robocompass.com>

After users sign-in, two additional menu items appear on the menu bar.

- Options Menu: Dropdown menu for file management commands.
- Open File: Open a saved RoboCompass file from the local drive.
- Download File: Download or save worksheets onto the local drive.
- Share URL: Generate a link to a worksheet for easy sharing.
- Embed: Embed worksheets with embed codes.

Share Url

URL: <http://www.robocompass.com/share?id=1yhp2c> Go

Embed

```
<iframe width="160" height="310"
src="http://www.robocompass.com/embed?id=1yhp2c3b0411"
frameborder="0" allowfullscreen></iframe>
```

-फोटोग्राफ साभार-

www.robocompass.com